

## STUDY ON VEHICULAR COMMUNICATIONS

**T.Ruth Supriya<sup>1</sup>, Gireesh kumarDixit<sup>2</sup>, B.Satyanarayana<sup>3</sup>**

<sup>1</sup>Research Scholar, Department of Computer Science, Shyam University,Dausa (India),

<sup>2</sup>Department of Computer Science, Shyam University,Dausa (India)

<sup>3</sup>Dept. of computer science and Engg., Principal,CMR institute of technology, Telangana(india)

**Abstract:** Accidents and traffic congestion are two common problems that the transportation industry faces. In spite of this, in recent years, it has also changed in terms of vehicle collaboration. This trend's main goal is to make roads safer by trying to foresee situations where there might be risk. Advances like Vehicle-to-Vehicle (V2V), Vehicle-to-Infrastructure (V2I), and Vehicle-to-Everything (V2X) expect to give correspondence models that vehicles can use in numerous application situations. The final result is a specially appointed network organization, with all cell phones with remote modules going about as hubs notwithstanding cars. Data is traded by means of the utilization of suitable correspondence conventions in communications between the different associated substances. Inspecting and assessing the most appropriate advances, applications, and correspondence conventions that will separate the future street foundations used via autos is the essential objective of the survey led for this article. The investigation's findings demonstrate the true advantages of technological cooperation for improving traffic safety.

**Keywords:** Vehicle-to-vehicle communications; intelligent transportation systems; road safety; and V2V, V2I, and V2X

### 1. Introduction

The use of intelligent systems has led to significant advancements in the transportation sector in recent years. Intelligent Transport Systems (ITSs) have replaced conventional transport arrangements [1-3]. Traffic congestion and accidents are the two key issues facing transport engineers, and these new technologies are helping to solve them. However, these technologies need to work together, enabling communication between and among vehicles, for example [4]. Data trade between the different associations included should follow fitting correspondence conventions, for example, IEEE 802.11p [5,6] and LTE-V2V [7,8] guidelines that work with vehicle moves [9,10]. Additional data can be found in the IEEE 802.11p norm, which was explicitly established for Wireless Access in Vehicular Environments (WAVE). Its will probably make V2V and V2I correspondences simpler. Its interesting engineering makes it simpler for frameworks and vehicles to collaborate and organize [11]. Information paces of 6 Mbps to 27 Mbps are accessible with IEEE 802.11p at a short radio transmission distance of around 300 m. Cell advances have been surveyed for use in vehicle correspondences as an option in contrast to IEEE 802.11p [12]. The Third-Age Organization Task (3GPP) normalization, which empowers productive message dissemination to various clients all through a geographic district at a very much made granularity, is the essential facilitator of such utilization. The fourth era of versatile cell frameworks is called Long haul Advancement (LTE), and the third era is prevalently known as the All inclusive Portable Telecom Framework (UMTS). A headway of UMTS supports speed and limit by using an elective radio connection point notwithstanding center organization upgrades. In the radio organization, the LTE highlights offer transmission scopes of up to 100 km, downlink top paces of 300 Mbps, and uplink top paces of 75 Mbps. The exchange dormancy is under 5 ms.

Extra conventions that can be utilized in vehicle correspondences incorporate IEEE 802.15.4/ZigBee [14], reasonably refreshed [15], and Bluetooth [13]. Decreasing association times and expanding gearbox range are the essential objectives of the multitude of guidelines referenced above, empowering legitimate activity in circumstances with high vehicle thickness and portability. Inside the subject of transportation research, the primary target of these advancements is to upgrade

street security by turning away possibly dangerous conditions. In this specific situation, the objective of the V2V (Vehicle-to-Vehicle), V2I (Vehicle-to-Infrastructure), and V2X (Vehicle-to-Everything) technologies is to offer correspondence models that vehicles can use in different application settings [16,17, 18, 19, 20]. The final result is an impromptu lattice organization, with cell phones with remote modules going about as hubs notwithstanding vehicles.

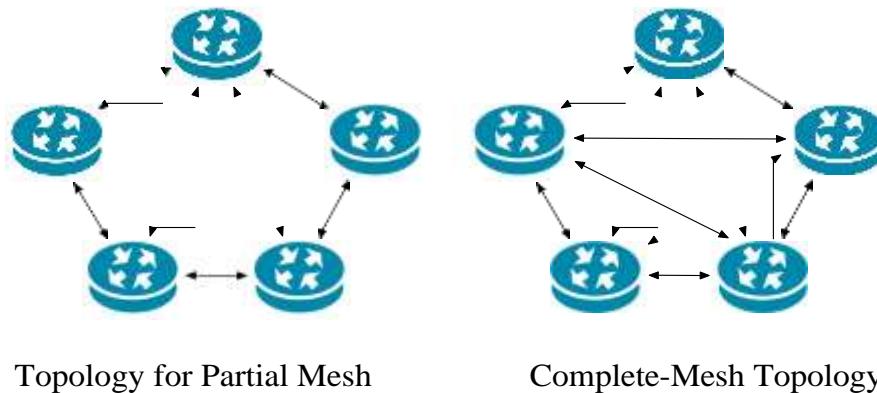
The essential objective of the audit led for this study is to show that the mix of these shrewd advancements into transport designing produces genuine advantages for traffic security. In the present car business, creating innovation answers for increment street wellbeing is one of the significant areas of consideration. In order to do this, a number of technologies, including assisted parking systems [25], driver notification systems [24], intelligent navigation systems [23], anti-collision sensors [22], and autonomous driving [26], have been included into the cars that are currently on the market. But each firm has its own unique technologies that don't work well with other manufacturers' equipment when it comes to installing it in their automobiles. For precisely these reasons, a global standard system that facilitates seamless and efficient integration across all of these services and applications is imperative to develop [27–30].

It is important to remember that V2X refers to all vehicle-related communications, including V2V and V2I. To further emphasise the unique qualities of each of these three communication domains, a separate analysis of each is conducted in the review conducted in this work. This document is organised as follows: Section 2 describes the primary technologies and applications that most effectively meet the requirements needed to actualize effective technological collaboration among vehicles, with a focus on vehicle-to-vehicle (V2V). Sections 3 and 4 introduce the main features of V2I and V2X, respectively. In Section 5, the paper's conclusions are discussed along with suggestions for further research.

## 2. Vehicle-To-Vehicle

Remote information correspondences between engine vehicles make up vehicle-to-vehicle (V2V) technology. This correspondence's fundamental objective is to deflect possible crashes by empowering moving vehicles to share position and speed information inside a specially appointed network [31]. The last option utilizes a decentralized association framework that can offer a cross section geography that is either completely or to some degree associated (Figure 1). Each hub in the main situation has an immediate association with each and every hub in the organization. In the subsequent situation, certain hubs can associate with each and every other hub, and the rest are simply connected to the hubs they consistently share most of their information with. Using this organization geography, network hubs can speak with neighboring hubs with whom they are straightforwardly associated (a solitary bounce, on account of a completely associated network) or select from different accessible ways to get to their objective (multi-jump, on account of a somewhat associated network). Furthermore reinforcing the organization construction's strength is this engineering. As a matter of fact, the courses are refreshed inside the sending tables to arrive at all objections in case of a hub breakdown or transitory disappointment.

Because of the prerequisite for actual associations between one hub and the others, this engineering was extremely exorbitant and testing to execute in the days when lattice networks were exclusively wired. These limitations are as of now not an issue in light of the fact that to the utilization of the advantages that remote correspondences achieved and the improvement of Remote Individual Region Organizations (WPANs). These organizations comprise of versatile, free hubs that are coupled to each other to frame an erratic measured chart (to some degree associated network organization). The singular hubs forward the bundles to one another, planning the progression of correspondences to each element in the organization as opposed to relying upon a base station. These hubs have the opportunity to move and orchestrate themselves anyway they like, notwithstanding the erratic and quick changes in remote geography. In addition, these organizations can work alone or related to the Web to offer additional administrations.



**Figure1.**Mesh architectures.

If a vehicle is worked to perform wellbeing mediations, for example, crisis slowing down, the driver might be told ahead of a looming crash or the actual vehicle might have the option to make a preventive move all alone [32]. Since installed sensors, cameras, and radars are currently the main parts that decide a vehicle's security, it is guessed that V2V correspondences will be essentially more compelling than the OEM's current implanted frameworks [33]. These mounted devices on the vehicle get specific boundaries, which are then utilized by the framework to respond to possibly perilous conditions. Generally, the movement speed, the partition from a hindrance, and the presence of a vehicle in the vulnerable side are the essential factors that are checked. Despite the fact that the innovations being utilized are turning out to be more trustworthy, calculation mistakes ought not be messed with. Alternately, V2V correspondence conventions will upgrade execution in the security space in light of the fact that, by empowering all vehicles to speak with each other, they will help the vehicle that is at serious risk (due to, for instance, a driver's rest, a breaking down part, a block in the path, and so on) in coming to a more reasonable conclusion about how to deal with the creating issue. Subsequently, every hub that makes up the lattice organization will basically gather information for the point of guaranteeing satisfactory security for both itself and its neighbors. Agreeable mindfulness is the name given to this system [34]. Anyway, as suggested in [35,36], it is useful to apply fitting coding procedures for ongoing information access. A rundown of the latest age of independent OEM security frameworks will give you an exhaustive comprehension of the multitude of innovations now available.

Coming up next are the fundamental OEM frameworks that are presently being used:

- Blind Spot Monitoring (BSM): this help framework utilizes radar sensors to watch out for the visually impaired regions apparent in the external back view mirrors. Contingent upon which side the vehicle in front passes, this framework utilizes a visual sign incorporated into the left and right rearview mirrors to make the driver aware of another vehicle's appearance.
- Anti-SchlupfRegierung (ASR), likewise alluded to as Programmed Soundness Control (ASC) or Traction Control System (TCS) [38]: this framework manages and controls how the wheels slide during speed increase. It works in basically the same manner to the homologous framework for slowing down control in that it empowers better control of footing during the beginning stage (as well as during the journey stage), contingent upon the condition of the street surface.
- Electronic Stability Programme (ESP) [39]: a contraption that participates for the situation of oversteer or understeer developments, or when the vehicle shows side effects of horizontal behaving (yaw). Accordingly, it allows the vehicle to keep on track and stay away from impediments.
- Forward Collision Warning (FCW) [40]: this framework watches out for the street utilizing

radar sensors. This innovation can recognize articles and measure the partition between the vehicle and likely barriers. On the off chance that the speed of the vehicle represents a gamble of a looming crash, the driver will be told through light signals or acoustic sensors on the installed show.

- Automatic Emergency Braking (AEB) [41]: when a crash is undeniable, this helped crisis stopping mechanism utilizes electronic steadiness control and upgraded driver help to dial back the vehicle and maybe reduce the effect's seriousness. In circumstances where the driver neglects to utilize an adequate number of brakes or neglects to slow down by any stretch of the imagination (for instance, since they are sleeping), the pre-crash framework diminishes the effect by situating various pieces of the vehicle. To safeguard the tenants in case of an upset, the belts are secured to their greatest length, air is siphoned into the airbags, the windows and sunroof are shut, and the brake marginally mediates to diminish influence viciousness while at the same time drawing the driver's consideration. On account of an episode, the dynamic head limitations, if fitted in the vehicle, are calculated forward to lessen whiplash harm.
- Brake Assist System (BAS) [42]: this is a functioning gadget that is joined to the vehicle's stopping mechanism and possibly draws in when there is a surprising crisis slowing down, for example, when the brake pedal is quickly discouraged yet not with enough power to actuate the antilock framework, or ABS. An electronic control component holds the wheels back from securing while at the same time slowing down, permitting the vehicle to be driven. In this occurrence, the BAS starts the programmed expansion in pedal strain until the ABS on each wheel works accurately, ensuring improved slowing down execution.
- Lane Departure Warning System(LDWS) [43]: this is a contraption that makes the driver heedlessness aware of the way that its path is being surpassed. It is turned on by a switch on the mid control area and sounds a little acoustic caution to alarm the driver in the event that the vehicle crosses a path line for reasons unknown — for instance, by not using the heading marker.

The cooperation between the V2V innovation and these prior security frameworks will bring about powerful administration of possible dangers on streets around the world. To further develop traffic the board, the new Intelligent Transport Systems (ITSs) will use data from vehicle-to-vehicle (V2V) communication. This will empower vehicles to interface with street foundation, for example, traffic signals or signs. Not long from now, these advancements may be required, which would assist with making more trustworthy self-driving autos on parkways. Notwithstanding, there are three essential difficulties to the sending of V2V correspondences and a wise vehicle framework: the necessity that automakers agree to security and functional rules; the affirmation of protection and classification of information sent in broadcast and multicast; and the financing expected for the creation and circulation of all innovation.

It is presently muddled who will pay for the turn of events and upkeep of the organization framework: public or confidential elements. Notwithstanding, it is useful to feature General Engines, BMW, Audi, Daimler, and Volvo as a portion of the top automakers dealing with ITS frameworks and V2V interchanges. Throughout recent years, innovative work endeavors for various vehicles around the world, especially in the USA, have zeroed in on the assessment of models connected with vehicle-to-vehicle (V2V) applications [44]. These endeavors have prompted the improvement of a few trial models that utilization different scientific strategies to gauge the natural effects — which are challenging to notice today because of the absence of guidelines — as well as the potential future effects coming about because of an extensive variety of speculative bond of uses in the field of vehicular correspondences. The United States Department of Transportation (USDOT) has delivered documentation on the creation and execution of the most modern applications. This documentation incorporates configuration records, source codes for models, framework determinations, and calculations [45]. A portion of the associated vehicle applications are displayed in Table 1, which is coordinated by

USDOT.

**Table1.** Applications for networked autos.

V2VSafety	AgencyData/Environment	SmartRoadside/Mobility
Emergency ElectronicBrakeLig hts(EEBL)	Probe-basedPavementMainten ance	WirelessInspectionSmartTruckP arking
Forward Collision Warning(FCW)	Probing Probing enabledTraffic	
IntersectionMovement Assist(IMA)	VehicleClassification-based TrafficStudies	IntelligentTrafficSignal System(I-SIG)
LeftTurnAssist (LTA)	CV-enabledTurningMovement &IntersectionAnalysis	SignalPriority (transit,freight)
BlindSpot/Lane ChangeWarning	CV-enabledOrigin-Destination Studies	CooperativeAdaptive CruiseControl(CACC)
CurveSpeed Warning	WorkZoneTraveler Information	Guidancefor Emergency
DoNotPass Warning(DNPW)	DynamicEco-Routing (light,vehicle,transit,freight)	EmergencyCommunications andEvacuation(EVAC)
VehicleTurning RightinFrontof	LowEmissionsZone Management	ConnectionProtection (T-CONNECT)
BusWarning (transit)	Eco-ICMDecision SupportSystem	Freight-Specific DynamicTravel
Queue Warning (Q-WARN)	Eco-Smart Parking	EmergencyVehicle Preemption(PREEMPT)

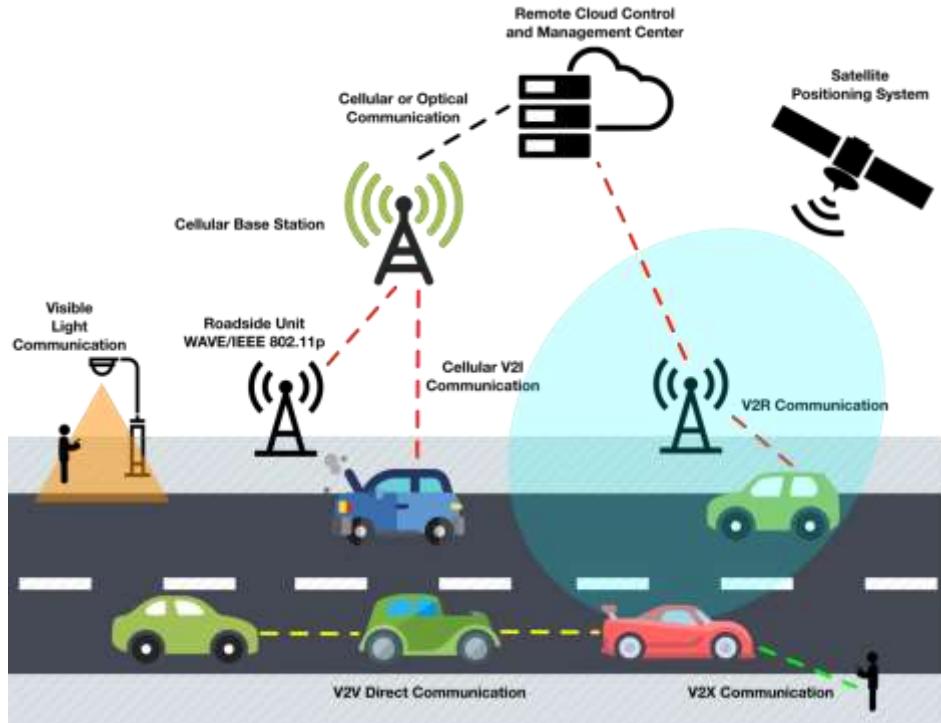
### 3. Vehicle-To-Infrastructure

The V2I correspondence model permits vehicles on the way to speak with the street framework, as opposed to the V2V correspondence model, which just allows data trade among vehicles. These components comprise of stopping meters, path markings, streetlights, cameras, traffic signals, and RFID perusers [46]. Dedicated Short-Range Communication (DSRC) frequencies are commonly utilized for remote, bidirectional, and information move V2I correspondences, same like in V2V [47]. Through an impromptu organization, this information is communicated from the framework's parts to the vehicle or the other way around. Using V2I sensors in the ITS, voyagers can get continuous counsel on street conditions, gridlock, mishaps on the course, the presence of building destinations, and parking spot accessibility. Additionally, factor speed limitations and changes to Signal Phase and Timing(SPaT) can be made by traffic oversight and the executives frameworks utilizing data accumulated from vehicles and foundation to diminish fuel use and further develop traffic stream [48]. The advancement of independent vehicles starts with the equipment, programming, and firmware that empower fitting correspondence among vehicles and framework.

The Government Parkway Organization (FHA) got V2I suggestions from the US Branch of Transportation in January 2017, fully intent on improving security and versatility and facilitating the utilization of correspondence advances [49]. The motivation behind these rules is to help state legislatures in arranging V2I activities and dealing with the information expected to back them up. As was at that point noted, state run administrations give monetary and asset related difficulties to the execution of these projects. Since the states' income from fuel duties and street tolls is lacking to cover these costs, a coordinated effort with the creators of the essential vehicle is required. This relationship could help the makers' business utilization of enormous information in correspondences.

### 4. Vehicle-To-Everything

The V2X is a speculation that finishes the recently examined V2V and V2I correspondence models. The last option incorporates other more particular types of correspondence like Vehicle-to-Pedestrian (V2P) [50], Vehicle-to-Roadside (V2R) [51], Vehicle-to-Device (V2D) [52], and Vehicle-to-Grid (V2G) [53]. It includes sending information from a vehicle to any element that can influence it, or the other way around. Figure 2 portrays an overall outline of the V2V, V2I, and V2X interchanges. The worldwide state of street security study [54] states that over 1.25 million people overall lose their lives in auto collisions every year. Vulnerable Road Users (VRUs) incorporate bikes, motorcyclists, and walkers, and they represented over portion of the fatalities [55]. It is critical to recollect that unfortunate street configuration defects and inappropriate partition from traffic significantly affect making the climate dangerous for the two vehicles and people on foot [56]. The interruption that comes from individuals utilizing their cellphones and headphones while walking around the road is another issue that ought not be trifled with, especially in metropolitan regions [57]. Subsequently, making an admonition framework for walkers is similarly fundamental.



**Figure2.** Communications between V2V, V2I, and V2X.

One of the essential objectives of V2X innovation is to work with successful and practical correspondence channels among autos and walkers with an end goal to lessen the quantity of mishaps, some of which are lethal. The Person on foot Impact Pedestrian Collision (PCW), which can use remote modules tracked down in cell phones, like Wi-Fi, Bluetooth, and Near Field Communication (NFC), has as of late been made [58,59]. A functioning security component for VRU has been remembered for [60] for of making walkers aware of looming risk in the location framework in light of remote modules contained in the PCW plan, for instance, as the Wi-Fi module contends. The Wi-Safe innovation is utilized to similar module in V2X correspondences [61], however it has an essential limit in that it is a unidirectional strategy, implying that notification are simply shipped off walkers. Interestingly, [63] utilizes Wi-Fi Direct [62], a shared remote innovation that empowers cell phones to talk with each other without going by means of a passage like cell phone towers. In any case, there are sure disservices to Wi-Fi-based techniques. At first, on the off chance that the Passageway/Client mode is being utilized, there will be an impressive power utilization. Also, the checking time frame's parcel conveyance rate and postpone figures are not comparable to those tracked down in the writing. Local innovation have so been expected for vehicle correspondences. In particular, for instance, General Engines evaluated the presentation of a vehicle with DSRC in V2X situations a couple of years prior [64, 65]. Concerning the V2X and PCW models, a camera-based preventive framework utilizing Visible Light Communication(VLC) can be executed [66-69]. In any case, the climate hugely affects this approach since it very well may be trying to get solid information assuming the climate or traffic conditions are awful. Also, defects in picture handling and other figuring limitations exist for three-layered acknowledgment. A driving help framework, as Adaptive Cruise Control (ACC) [70] and the AEB [71], that utilizes millimeter-wave radar [72], LiDAR (Laser Imaging Location and Running) [73], and other specific sensors in the vehicle can be another PCW arrangement. By estimating the distinction in time and recurrence between the signs sent and got, these sensors decide the general speed and distance from objects. The innovation is considered lacking in complex situations because of an impediment that is addressed by any powerless signs darkened by commotion or by the application at high travel speeds and the distance between vehicles. An arrangement in light of Bluetooth Low Energy (BLE) [74] can be utilized to get around Wi-Fi, VLC, and control sensor impediments. Since it empowers bidirectional correspondences with

minimal measure of force utilization and with adequate gathering values, this remote standard can be useful in PCW circumstances. Also, it is pre-introduced on all of the most current cell phones and looks to lay out the Internet of Things (IoT) correspondence standard [75]. In conclusion, considering the advancement of LTE-V2X and the impending 5G [76], completely robotized driving and state of the art vehicular administrations can be accomplished with cooperative development across ventures.

## 5. Conclusions

The short term is fixated on the worldwide execution of ITS frameworks on streets. To do this, updating all or a portion of the ongoing infrastructure will be important. Along these lines, to get the financing expected for the modernization of the entire street organization, all public states should offer public-private associations. These speculations ought to in a perfect world return a benefit that is predictable with government spending. Since most of utilizations in transport frameworks are generally conveyed through network information assortment, suitable correspondence network plan and the board is a critical initial step. This goal will be pivotal to guaranteeing that these frameworks are dependable and strong. Apparently the plan might in any case reach out as long as it takes to make reasonable models are more practical as far as calculations, scientific details, advancement models, and probabilistic strategies.

A significant pattern in the essential areas of interest for the present vehicle business is the participation among vehicles and, all the more comprehensively, among them and all types of transportation gear. The objective is to build driver and traveler solace, wellbeing, and perhaps amusement. The survey directed for this paper has analyzed the fundamental frameworks, applications, and conventions that best fulfill the necessities required for the acknowledgment of powerful mechanical participation at the assistance of street security, beginning with the advancements utilized in the present vehicles, which might have the option to autonomously capability. Verifiably, V2V, V2I, and V2X interchanges are among the ideal models that are useful for this reason.

To completely carry out the purported Internet of Things (IoT), new ITS advances should be considerably more successfully coordinated with portable organizations that are now set up or that will be created before long. This will uphold new cloud-based administrations and Software Defined Networks (SDN), delivering perpetually modern administrations. To accomplish the broadest materialness and useful execution, these organizations should be embraced in ITS applications. To cover the entire street organization of each state, it will be important to apply the scattering of ITS innovation to more unfamiliar streets, like those in provincial or low-thickness regions. Group of people yet to come portable correspondence frameworks, including the 5G, and Gadget to-Gadget (D2D) interchanges could guarantee network inclusion in circumstances when it can't be upheld. Also, online entertainment use and the execution of publicly supporting strategies might give gainful help to asset the executives in ITS applications. Then again, huge confidential organizations will actually want to oversee gigantic volumes of information from connected vehicles and cell phones to send off new showcasing and deals crusades.

In outline, in view of the examination led for this paper, Table 2 presents the objectives and difficulties related with the boundless utilization of vehicular correspondences. To work on the execution of ITS framework tasks, keeping up with the street surface and signage will be an essential part. Since just a little piece of the world's street framework is currently ready for V2X correspondences and major monetary assets are required for street enhancements, the essential obstruction in this occasion is cost. Upgrading the innovation framework, which incorporates full and complete activity of V2V, V2I, and V2X correspondences, is one more evenhanded to be achieved. Be that as it may, the test lies not simply in the potentially perplexing huge scope execution yet additionally without even a trace of a universally acknowledged norm. Large information the executives and examination done well will without a doubt be truly productive since it might bring about both the recovery of more unambiguous

data using complex scientific devices and a monetary return for possible confidential financial backers. However, all of this should guarantee the security of the information. All in all, it is clear that the combination and participation between ITS frameworks and the innovation foundation would yield benefits concerning improving the proficiency of transportation framework tasks and possibly encouraging the production of novel applications. Yet again the key hindrances are the monetary ramifications, the trouble of enormous scope organization, and the shortfall of a typical norm.

**Table2.**Advantages and disadvantages of upcoming vehicle communications.

Feature	Advantages	Downsides
<i>Maintenance of roadsurface and signs</i>	Improvement of ITS systems performance	-Economic costs
<i>Technological infrastructure</i>	- Full operation of V2V, V2I, and V2X communications	- Complexity of large-scale implementation - Standardization
<i>Big Data management</i>		- Ensured data privacy
<i>Integration between ITS systems and technological infrastructure</i>	- Economic returns for possible private investors - More information than just analysis - Improved performance in system operation - Development of possible new future applications	- Complexity of large-scale implementation - Standardization - Economic costs

## References

1. Ghosh, R.; Pragathi, R.; Ullas, S.; Borra, S. Intelligent transportation systems: A survey. In Proceedings of the 2017 International Conference on Circuits, Controls, and Communications (CCUBE), Bangalore, India, 15–16 December 2017; pp. 160–165.
2. Luckow, A.; Kennedy, K. Data Infrastructure for Intelligent Transportation Systems. In *Data Analytics for Intelligent Transportation Systems*; Chowdhury, M., Apon, A., Dey, K., Eds.; Elsevier: Amsterdam, The Netherlands, 2017; Chapter 5, pp. 113–129.

3. Alam,M.;Ferreira,J.;Fonseca,J.IntroductiontoIntelligentTransportationSystems.In *Intelligent Transportation Systems: Dependable Vehicular Communications for Improved Road Safety*; Alam, M., Ferreira, J., Fonseca, J., Eds.; Springer International Publishing:Cham, Switzerland, 2016; pp. 1–17.
4. Martin-Vega, F.J.; Soret, B.; Aguayo-Torres, M.C.; Kovacs, I.Z.; Gomez, G. Geolocation-Based Access for Vehicular Communications: Analysis and Optimization via Stochastic Geometry. *IEEE Trans. Veh. Technol.* **2018**, *67*, 3069–3084. [[CrossRef](#)]
5. Han,C.;Dianati,M.;Tafazolli,R.;Kernchen,R.;Shen,X. Analytical Study of the IEEE 802.11 p MAC Sublayer in Vehicular Networks. *IEEE Trans. Intell. Transp. Syst.* **2012**, *13*, 873–886. [[CrossRef](#)]
6. Bazzi,A.;Campolo,C.;Masini,B.M.;Molinaro,A.;Zanella,A.; Berthet, A.O. Enhancing Cooperative Driving in IEEE 802.11 Vehicular Networks Through Full-Duplex Radios. *IEEE Trans. Wirel. Commun.* **2018**, *17*, 2402–2416. [[CrossRef](#)]
7. Molina-Masegosa, R.;Gozalvez, J. LTE-V for Sidelink 5G V2X Vehicular Communications: A New 5G Technology for Short-Range Vehicle-to-Everything Communications. *IEEE Veh. Technol. Mag.* **2017**, *12*, 30–39. [[CrossRef](#)]
8. Bazzi, A.; Cecchini, G.; Zanella, A.; Masini, B.M. Study of the Impact of PHY and MAC Parameters in 3GPPC-V2V Mode4. *IEEE Access* **2018**, *6*, 71685–71698. [[CrossRef](#)]
9. Park, S.; Kim, B.; Yoon, H.; Choi, S. RA-eV2V: Relaying systems for LTE-V2V communications. *J. Commun. Netw.* **2018**, *20*, 396–405. [[CrossRef](#)]
10. Bazzi, A.; Masini, B.M.; Zanella, A.; Thibault, I. On the Performance of IEEE 802.11p and LTE-V2V for the Cooperative Awareness of Connected Vehicles. *IEEE Trans. Veh. Technol.* **2017**, *66*, 10419–10432. [[CrossRef](#)]
11. Noor-A-Rahim, M.; Ali, G.G.M.N.; Nguyen, H.; Guan, Y.L. Performance Analysis of IEEE 802.11p Safety Message Broadcast with and without Relaying at Road Intersection. *IEEE Access* **2018**, *6*, 23786–23799. [[CrossRef](#)]
12. He, J.; Tang, Z.; Fan, Z.; Zhang, J. Enhanced Collision Avoidance for Distributed LTE Vehicle to Vehicle Broadcast Communications. *IEEE Commun. Lett.* **2018**, *22*, 630–633. [[CrossRef](#)]
13. Bluetooth Special Interest Group. Bluetooth Core Specification Versions: 4.0; 4.1; 4.2. June 2010; December 2013; December 2014. Available online: <https://www.bluetooth.com/specifications/bluetooth-core-specification> (accessed on 29 December 2018).
14. IEEE. *IEEE Standard for Information Technology—Telecommunications and Information Exchange between Systems—Local and Metropolitan Area Networks—Specific Requirements Part 15.4: Wireless Medium Access Control (MAC) and Physical Layer (PHY) Specifications for Low-Rate Wireless Personal Area Networks (WPANs)*; Technical Report; IEEE: Piscataway, NJ, USA, 2006.
15. Iordache, V.; Gheorghiu, R.A.; Minea, M.; Cormos, A.C. Field testing of Bluetooth and ZigBee technologies for vehicle-to-infrastructure applications. In Proceedings of the 2017 13th International Conference on Advanced Technologies, Systems and Services in Telecommunications (TELSIKS), Nis, Serbia, 18–20 October 2017; pp. 248–251.
16. Abbasi, I.A.; Shahid Khan, A. A Review of Vehicle to Vehicle Communication Protocols for VANETs in the Urban Environment. *Future Internet* **2018**, *10*, 14. [[CrossRef](#)]
17. Demba, A.; Möller, D.P.F. Vehicle-to-Vehicle Communication Technology. In Proceedings of the 2018 IEEE International Conference on Electro/Information Technology (EIT), Rochester, MI, USA, 3–5 May 2018; pp. 0459–0464.
18. Silva,C.M.;Silva,L.D.;Santos,L.A.L.;Sarubbi,J.F.M.;Pitsillides,A.Broadening Understanding on

Managing the Communication Infrastructure in Vehicular Networks: Customizing the Coverage Using the Delta Network. *Future Internet* **2018**, *11*, 1. [[CrossRef](#)]

19. Noh, S.; An, K.; Han, W. Toward highly automated driving by vehicle-to-infrastructure communications. In Proceedings of the 2015 15th International Conference on Control, Automation and Systems (ICCAS), Busan, Korea, 13–16 October 2015; pp. 2016–2021.
20. Corchero, C.; Sanmarti, M. Vehicle-to-Everything (V2X): Benefits and Barriers. In Proceedings of the 2018 15th International Conference on the European Energy Market (EEM), Lodz, Poland, 27–29 June 2018; pp. 1–4.
21. Bian, K.; Zhang, G.; Song, L. Toward Secure Crowd Sensing in Vehicle-to-Everything Networks. *IEEE Netw.* **2018**, *32*, 126–131. [[CrossRef](#)]

22. Sanjana, T.; Fuad, K.A.A.; Habib, M.M.; Rumel, A.A. Automated anti-collision system for automobiles. In Proceedings of the 2017 International Conference on Electrical, Computer and Communication Engineering (ECCE), Cox's Bazar, Bangladesh, 16–18 February 2017; pp. 866–870.

23. Zhang, X.; Zeng, Q.; Meng, Q.; Xiong, Z.; Qian, W. Design and realization of a mobile seamless navigation and positioning system based on Bluetooth technology. In Proceedings of the 2016 IEEE Chinese Guidance, Navigation and Control Conference (CGNCC), Nanjing, China, 12–14 August 2016; pp. 1790–1793.

24. Tijerina, L.; Blommer, M.; Curry, R.; Swaminathan, R.; Kochhar, D.S.; Talamonti, W. An Exploratory Study of Driver Response to Reduced System Confidence Notifications in Automated Driving. *IEEE Trans. Intell. Veh.* **2016**, *1*, 325–334. [\[CrossRef\]](#)

25. Liu, M.; Naoum-Sawaya, J.; Gu, Y.; Lecue, F.; Shorten, R. A Distributed Markovian Parking Assist System. *IEEE Trans. Intell. Transp. Syst.* **2018**, *99*, 1–11. [\[CrossRef\]](#)

26. Arena, F.; Ticali, D. The development of autonomous driving vehicles in tomorrow's smart cities mobility. *AIP Conf. Proc.* **2018**, *2040*, 140007.

27. Silva, C.M.; Masini, B.M.; Ferrari, G.; Thibault, I. A Survey on Infrastructure-Based Vehicular Networks. *Mob. Inf. Syst.* **2017**, *2017*, 6123868. [\[CrossRef\]](#)

28. Festag, A. Cooperative intelligent transport systems standards in Europe. *IEEE Commun. Mag.* **2014**, *52*, 166–172. [\[CrossRef\]](#)

29. Masini, B.M.; Bazzi, A.; Zanella, A. A Survey on the Roadmap to Mandate on Board Connectivity and Enable V2V-Based Vehicular Sensor Networks. *Sensors* **2018**, *18*, 2207. [\[CrossRef\]](#)

30. Sjoberg, K.; Andres, P.; Buburuzan, T.; Brakemeier, A. Cooperative Intelligent Transport Systems in Europe: Current Deployment Status and Outlook. *IEEE Veh. Technol. Mag.* **2017**, *12*, 89–97. [\[CrossRef\]](#)

31. Anaya, J.J.; Talavera, E.; Jimenez, F.; Zato, J.G.; Gomez, N.; Naranjo, J.E. GeoNetworking based V2V Mesh Communications over WSN. In Proceedings of the 16th International IEEE Conference on Intelligent Transportation Systems (ITSC2013), The Hague, The Netherlands, 6–9 October 2013; pp. 2421–2426.

32. Zhang, E.D.L. Vehicle Stability Control System of Emergency Brake on Split-Mu Road. In Proceedings of the 2017 9th International Conference on Intelligent Human-Machine Systems and Cybernetics (IHMSC), Hangzhou, China, 26–27 August 2017; Volume 1, pp. 252–255.

33. Tornell, S.M.; Patra, S.; Calafate, C.T.; Cano, J.; Manzoni, P. A novel On-Board Unit to accelerate the penetration of ITS services. In Proceedings of the 2016 13th IEEE Annual Consumer Communications Networking Conference (CCNC), Las Vegas, NV, USA, 9–12 January 2016; pp. 467–472.

34. Boban, M.; d'Orey, P.M. Exploring the Practical Limits of Cooperative Awareness in Vehicular Communications. *IEEE Trans. Veh. Technol.* **2016**, *65*, 3904–3916. [\[CrossRef\]](#)

35. Ali, G.G.M.N.; Noor-A-Rahim, M.; Rahman, M.A.; Samantha, S.K.; Chong, P.H.J.; Guan, Y.L. Efficient Real-Time Coding-Assisted Heterogeneous Data Access in Vehicular Networks. *IEEE Internet Things J.* **2018**, *5*, 3499–3512. [\[CrossRef\]](#)

36. Ali, G.G.M.N.; Noor-A-Rahim, M.; Chong, P.H.J.; Guan, Y.L. Analysis and Improvement of Reliability Through Coding for Safety Message Broadcasting in Urban Vehicular Networks. *IEEE Trans. Veh. Technol.* **2018**, *67*, 6774–6787. [\[CrossRef\]](#)

37. Liu, G.; Wang, L.; Zou, S. A radar-based blind spot detection and warning system for driver

assistance.In Proceedings of the 2017 IEEE 2nd Advanced Information Technology, Electronic and Automation ControlConference (IAEAC),Chongqing, China,25–26March 2017;pp.2204–2208.

38. Cao, W.; Wu, Y.; Zhou, E.; Li, J.; Liu, J. Reliable Integrated ASC and DYC Control of All-Wheel-Independent-DriveElectric VehiclesoverCANUsingACodesignMethodology.*IEEEAccess***2018**,7,6047–6059.[[CrossRef](#)]

39. Wang,C.;Song,C.;Li,J.ResearchonKeyStateParametersEstimationofElectricVehicleESPBasedo n Multi-sensor.In Proceedings of the 2015 Fifth International Conference on Instrumentation andMeasurement, Computer, Communication and Control (IMCCC), Qinhuangdao, China, 18–20 September2015;pp.29–32.

40. Lu, Y.; Yuan, Y.; Wang, Q. Forward Vehicle Collision Warning Based on Quick Camera Calibration.In Proceedings of the 2018 IEEE International Conference on Acoustics, Speech and Signal Processing(ICASSP),Calgary,AB,Canada,15–20April2018;pp.2586–2590.

41. Chao, C.; Qin, X. Research of vehicle automatic emergency braking system evaluation methods.In Proceedings of the IET International Conference on Intelligent and Connected Vehicles (ICV 2016),Chongqing,China,22–23September2016;pp.1–9.

42. Kusano, K.D.; Gabler, H.C. Safety Benefits of Forward Collision Warning, Brake Assist, and AutonomousBrakingSystemsinRear-EndCollisions.*IEEE Trans.Intell.Transp.Syst.***2012**,13,1546–1555.[[CrossRef](#)]

43. Vinuchandran, A.V.; Shanmughasundaram, R.A real-time lane departure warning and vehicle detectionsystem using monoscopic camera.In Proceedings of the 2017 International Conference on IntelligentComputing,InstrumentationandControlTechnologies(ICICICT),Kannur,India,6–7July2017;pp.1565–1569.

44. Vehicle-To-Vehicle (V2V) Communication Market, by Connectivity Type, Deployment Type, Applications,End-Use, and Geography—Insights, Size, Share, Opportunity Analysis, and Industry Forecast till 2025.*CoherentMarketInsight*,26October2017.

45. DepartmentofTransportationoftheUnitedStatesofAmerica. Vehicle-To-Vehicle(V2V)CommunicationsforSafety. Availableonline:[https://www.its.dot.gov/research\\_archives/safety/v2v\\_comm\\_plan.htm](https://www.its.dot.gov/research_archives/safety/v2v_comm_plan.htm)(accessedon29December2018).

46. Jurgen,R.V2V/V2ICommunicationsforImprovedRoadSafetyandEfficiency;SAE:Warrendale,PA,USA, 2012;pp.i–viii.

47. Rahman, K.A.; Tepe, K.E. Towards a cross-layer based MAC for smooth V2V and V2I communications forsafety applications in DSRC/WAVE based systems.In Proceedings of the 2014 IEEE Intelligent VehiclesSymposium Proceedings,Dearborn,MI, USA,8–11June 2014;pp.969–973.

48. Sepulcre, M.; Gozalvez, J.; Altintas, O.; Kremer, H. Context-aware heterogeneous V2I communications.In Proceedings of the 2015 7th International Workshop on Reliable Networks Design and Modeling (RNDM),Munich,Germany,5–7October2015;pp.295–300.

49. DepartmentofTransportationoftheUnitedStatesofAmerica. Vehicle-To-Infrastructure(V2I)Resources. Availableonline:<https://www.its.dot.gov/v2i/index.htm>(accessed on29December2018).

50. Tahmasbi-Sarvestani, A.; Mahjoub, H.N.; Fallah, Y.P.; Moradi-Pari, E.; Abuchaar, O.Implementation andEvaluationofaCooperativeVehicle-to-PedestrianSafetyApplication.*IEEEIntell.Transp.Syst.Mag.***2017**,9,62–75.[[CrossRef](#)]

51. Wu, C.; Yoshinaga, T.; Ji, Y.; Zhang, Y.Computational Intelligence Inspired Data Delivery for Vehicle-to-RoadsideCommunications.*IEEETrans. Veh. Technol.***2018**,67,12038–12048.[[CrossRef](#)]

52. Jomaa, D.; Yella, S.; Dougherty, M.A Comparative Study between Vehicle Activated Signs and SpeedIndicatorDevices.*Transp.Res.Procedia***2017**, 22, 115–123.[[CrossRef](#)]

53. Endo, M.; Tanaka, K.Evaluation of Storage Capacity of Electric Vehicles for Vehicle to Grid ConsideringDriver’s Perspective.In Proceedings of the 2018 IEEE International Conference on

Environment and Electrical Engineering and 2018 IEEE Industrial and Commercial Power Systems Europe (EEEIC/I CPSEurope), Palermo, Italy, 12–15 June 2018; pp. 1–5.

54. World Health Organization. *Global Status Report on Road Safety*; World Health Organization: Geneva, Switzerland, 2015.

55. Matsumoto, S.; Ohhigashi, N.; Hasuike, T. Developing a Transportation Support System for Vulnerable Road Users in Local Community. In Proceedings of the 2016 5th IIAI International Congress on Advanced Applied Informatics (IIAI-AAI), Kumamoto, Japan, 10–14 July 2016; pp. 797–800.

56. Pau, G.; Campisi, T.; Canale, A.; Severino, A.; Collotta, M.; Tesoriere, G. Smart Pedestrian Crossing Management at Traffic Light Junctions through a Fuzzy-Based Approach. *Future Internet* **2018**, *10*, 15.

57. Oliveira, T.R.; Silva, C.M.; Macedo, D.F.; Nogueira, J.M.S. SNVC: Social networks for vehicular certification. *Comput. Netw.* **2016**, *111*, 129–140. [[CrossRef](#)]

58. Kuo, Y.; Fu, C.; Tsai, C.; Lin, C.; Chang, G. Pedestrian Collision Warning of Advanced Driver Assistance Systems. In Proceedings of the 2016 International Symposium on Computer, Consumer and Control (IS3C), Xi'an, China, 4–6 July 2016; pp. 740–743.

59. Jung, H.; Choi, M.; Soon, K.; Jung, W.Y. End-to-end pedestrian collision warning system based on a convolutional neural network with semantic segmentation. In Proceedings of the 2018 IEEE International Conference on Consumer Electronics (ICCE), Las Vegas, NV, USA, 12–14 January 2018; pp. 1–3.

60. Dhongde, K.; Song, S.; Choi, B.; Park, H. WiFiHonk: Smartphone-Based Beacon Stuffed WiFi Car 2X-Communication System for Vulnerable Road User Safety. In Proceedings of the 2014 IEEE 79th Vehicular Technology Conference (VTC Spring), Seoul, Korea, 18–21 May 2014; pp. 1–5.

61. Fire Angel. Wi-Safe Connect, 2018. Available online: <https://www.wi-safeconnect.com/uk/> (accessed on 29 December 2018).

62. Lee, J.H.; Park, M.; Shah, S.C. Wi-Fi direct based mobile ad hoc network. In Proceedings of the 2017 2nd International Conference on Computer and Communication Systems (ICCCS), Krakow, Poland, 11–14 July 2017; pp. 116–120.

63. Kinkade, S.; Naughton, C.; Pines, S.; Eagles, R. Honda Demonstrates Advanced Vehicle-To-Pedestrian and Vehicle-To-Motorcycle Safety Technologies. 2013. Available online: <https://www.prnewswire.com/news-releases/honda-demonstrates-advanced-vehicle-to-pedestrian-and-vehicle-to-motorcycle-safety-technologies-221495031.html> (accessed on 29 December 2018).

64. Nguyen, H.; Noor-A-Rahim, M.; Liu, Z.; Jamaludin, D.; Guan, Y.L. A Semi-Empirical Performance Study of Two-Hop DSRC Message Relaying at Road Intersections. *Information* **2018**, *9*, 147. [[CrossRef](#)]

65. General Motors. GM Developing Wireless Pedestrian Detection Technology. 2012. Available online: [https://media.gm.com/media/us/en/gm/home.detail.html/content/Pages/news/us/en/2012/Jul/0726\\_pedestrian.html](https://media.gm.com/media/us/en/gm/home.detail.html/content/Pages/news/us/en/2012/Jul/0726_pedestrian.html) (accessed on 29 December 2018).

66. Mare, R.M.; Marte, C.L.; Cugnasca, C.E. Visible Light Communication Applied to Intelligent Transport Systems: An Overview. *IEEE Lat. Am. Trans.* **2016**, *14*, 3199–3207. [[CrossRef](#)]

67. Cailean, A.; Dimian, M. Current Challenges for Visible Light Communications Usage in Vehicle Applications: A Survey. *IEEE Commun. Surv. Tutor.* **2017**, *19*, 2681–2703. [[CrossRef](#)]

68. Yamazato, T.; Takai, I.; Okada, H.; Fujii, T.; Yendo, T.; Arai, S.; Andoh, M.; Harada, T.; Yasutomi, K.; Kagawa, K.; et al. Image-sensor-based visible light communication for

automotive applications. *IEEE Commun. Mag.* **2014**, *52*, 88–97. [[CrossRef](#)]

- 69. Bazzi, A.; Masini, B.M.; Zanella, A.; Calisti, A. Visible light communications as a complementary technology for the internet of vehicles. *Comput. Commun.* **2016**, *93*, 39–51. [[CrossRef](#)]
- 70. Anayor, C.; Gao, W.; Odekunle, A. Cooperative Adaptive Cruise Control of A Mixture of Human-driven and Autonomous Vehicles. In Proceedings of the IEEE SoutheastCon 2018, St. Petersburg, FL, USA, 19–22 April 2018; pp. 1–3.
- 71. Rezwan, M.S.; Islam, M.A.; Islam, M.M.; Hasan, M.R. Vehicle Breaking Support System. In Proceedings of the 2018 3rd International Conference for Convergence in Technology (I2CT), Pune, India, 6–7 April 2018; pp. 1–4.
- 72. Asuzu, P.; Thompson, C. Road condition identification from millimeter-wave radar backscatter measurements. In Proceedings of the 2018 IEEE Radar Conference (RadarConf18), Oklahoma City, OK, USA, 23–27 April 2018; pp. 0012–0016.
- 73. Yoshioka, M.; Suganuma, N.; Yoneda, K.; Aldibaja, M. Real-time object classification for autonomous vehicle using LIDAR. In Proceedings of the 2017 International Conference on Intelligent Informatics and Biomedical Sciences (ICIIBMS), Okinawa, Japan, 24–26 November 2017; pp. 210–211.
- 74. Bronzi, W.; Derrmann, T.; Castignani, G.; Engel, T. Towards characterizing Bluetooth discovery in a vehicular context. In Proceedings of the 2016 IEEE Vehicular Networking Conference (VNC), Columbus, OH, USA, 8–10 December 2016; pp. 1–4.
- 75. Collotta, M.; Pau, G.; Talty, T.; Tonguz, O.K. Bluetooth 5: A Concrete Step Forward toward the IoT. *IEEE Commun. Mag.* **2018**, *56*, 125–131. [[CrossRef](#)]

Chen, S.; Hu, J.; Shi, Y.; Peng, Y.; Fang, J.; Zhao, R.; Zhao, L. Vehicle-to-Everything (v2x) Services Supported by LTE-Based Systems and 5G. *IEEE Commun. Stand. Mag.* **2017**, *1*, 70–76